

Closed-Form Design of Maxflat Fractional Delay IIR Filters

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1 Introduction

Fractional delay (FD) filters are an important class of digital filters, and are useful in various signal processing applications [1]. In this paper, the closed-form solution is proposed for the maximally flat (maxflat) FD IIR filters, which is directly derived by solving a linear system of Vandermonde equations.

2 Fractional Delay Filters

Let $H(z)$ be the transfer function of IIR filters;

$$H(z) = \sum_{n=0}^N a_n z^{-n} / \sum_{m=0}^M b_m z^{-m}, \quad (1)$$

where N and M are degree of numerator and denominator, a_n, b_m are real filter coefficients, and $b_0 = 1$.

The desired frequency response of FD filters is given by

$$H_d(e^{j\omega}) = e^{-j(K+p)\omega}, \quad (2)$$

where K is an integer delay, and p is a fractional delay in the range $[-0.5, 0.5]$. Therefore, the design problem of FD filters is the approximation of $H(e^{j\omega})$ to $H_d(e^{j\omega})$ in the specified criterion, e.g., in the minimax or maxflat sense.

3 Maxflat FD IIR Filters

To obtain a maxflat FD filter at $\omega = 0$, the frequency response of $H(z)$ must satisfy

$$\left. \frac{\partial^r H(e^{j\omega})}{\partial \omega^r} \right|_{\omega=0} = \left. \frac{\partial^r H_d(e^{j\omega})}{\partial \omega^r} \right|_{\omega=0}, \quad (3)$$

for $r = 0, 1, \dots, N + M$. It is known that Eq.(3) is equivalent to

$$\begin{aligned} \left. \frac{\partial^r \{H(e^{j\omega})e^{j(K+p)\omega}\}}{\partial \omega^r} \right|_{\omega=0} &= \left. \frac{\partial^r \{H_d(e^{j\omega})e^{j(K+p)\omega}\}}{\partial \omega^r} \right|_{\omega=0} \\ &= \begin{cases} 1 & (r = 0) \\ 0 & (r = 1, 2, \dots, N + M) \end{cases}. \end{aligned} \quad (4)$$

It is obtained from Eq.(1) that

$$H(e^{j\omega})e^{j(K+p)\omega} = \frac{\sum_{n=0}^N a_n e^{j(K+p-n)\omega}}{\sum_{m=0}^M b_m e^{-jm\omega}} = \frac{N(\omega)}{D(\omega)}. \quad (5)$$

Therefore, by taking r th derivatives of Eq.(5) at $\omega = 0$, it can be seen that the condition in (4) is equivalent to

$$\left. \frac{\partial^r N(\omega)}{\partial \omega^r} \right|_{\omega=0} = \left. \frac{\partial^r D(\omega)}{\partial \omega^r} \right|_{\omega=0} \quad (r = 0, 1, \dots, N + M), \quad (6)$$

which derives a system of linear equations as follows;

$$\sum_{n=0}^N (K + p - n)^r a_n = \sum_{m=0}^M (-m)^r b_m, \quad (7)$$

for $r = 0, 1, \dots, N + M$. It should be noted that the coefficient matrix in Eq.(7) is the Vandermonde matrix with distinct elements in the case of $p \neq 0$. Therefore, there is always a unique solution since $b_0 = 1$. By using the Cramer's rule, we can obtain the presentation of the filter coefficient as a quotient of two Vandermonde's determinants. Therefore, a closed-form solution is obtained as

$$\begin{cases} a_n = (-1)^{n+1} \frac{M!}{n!(N-n)!} \frac{\prod_{i=0}^N (i - K - p)}{\prod_{i=0}^M (i - n + K + p)} \\ b_m = (-1)^m \frac{M!}{m!(M-m)!} \frac{\prod_{i=0}^N (i - K - p)}{\prod_{i=0}^N (i - m - K - p)} \end{cases}. \quad (8)$$

Once N, M, K and p are given, a set of filter coefficients a_n and b_m can be easily calculated by using Eq.(8). If we set $M = 0$ in Eq.(8), then the maxflat FD FIR filters proposed in [3] and [4] are obtained. Also if $N = M$, we have $a_n = b_{N-n}$, thus the resulting filters become the maxflat allpass filters proposed in [2]. Therefore, it is clear that the existing maxflat FD FIR and allpass filters are two special cases of the proposed maxflat FD IIR filters.

4 Conclusion

In this paper, we have proposed a new closed-form solution for the maxflat FD IIR filters. The filter coefficients have been directly derived by solving a linear system of Vandermonde equations. This new class of maxflat FD IIR filters include the existing maxflat FD FIR and allpass filters as special cases.

References

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